

A Cyclic Extension of Heegaard Splittings

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Presentation I

Preliminaries

Definition: A 3-Manifold is a three-dimensional topological space in which each point has a neighborhood that is homeomorphic to an open subset of three-dimensional Euclidean space.

Example: The 3-Sphere, S^3 , which is the set of all points in four-dimensional Euclidean space equidistant from a center point.

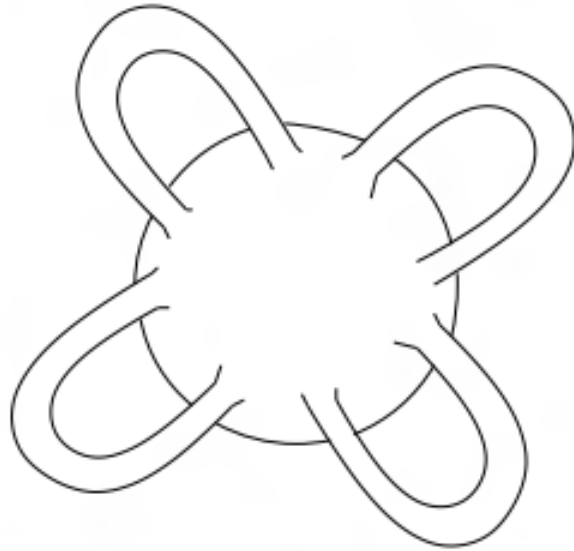
Preliminaries

Definition: A Handlebody is a topological object that is diffeomorphic to a regular neighborhood of a set of circles in $\mathbb{R}^3$ that are connected at a single common point.

If this set contains g circles, we say that the handlebody has genus g .

Preliminaries

Example: A handlebody of genus 4



Preliminaries

Definition: A Heegaard Splitting (or Heegaard Decomposition) of a closed oriented 3-manifold M is a pair of handlebodies H_0 and H_1 such that $M = H_0 \cup H_1$ and $H_0 \cap H_1 = \partial H_0 = \partial H_1$ (here ∂H_i indicates the boundary of H_i).

Alternatively, given two handlebodies H_0 and H_1 , we can 'glue' them along their common boundary to get a closed oriented 3-manifold.

Preliminaries

Theorem: Every closed oriented 3-Manifold admits a Heegaard Splitting.

Proof: Let M be such a 3-Manifold and consider a triangulation of M . This induces a three-dimensional graph structure on M . We construct a Heegaard Splitting as follows: Replace each vertex of the triangulation by a ball and each edge by a cylinder. Let H_0 be the union of these objects and let $H_1 = M \setminus H_0$.

Preliminaries

Here we consider smooth functions $f: M^n \rightarrow \mathbb{R}$ where M^n is an n -dimensional manifold.

Recall that a point P is a critical point of f if all of the partial derivatives of f vanish at P .

Also recall that the Hessian Matrix of f at P , $H(P)$, is given by the second partial derivatives where $H_{ij} = \partial^2 f / \partial x_i \partial x_j$.

P is non-degenerate if $H(P)$ is non-singular

Preliminaries

Definition: We say that the function $f: M^n \rightarrow \mathbb{R}$ is a Morse Function if all of its critical points are non-degenerate.

Definition: The index of a critical point P is the number of negative eigenvalues in the diagonalization of $H(P)$ with respect to a basis of its eigenvectors.

So a local min has index 0 and a local max has index n

A Morse-Theoretic Approach

Given a closed oriented 3-Manifold M , a morse function $f: M \rightarrow \mathbb{R}$ induces a Heegaard Splitting of M . This is because the inverse image of any regular (non-critical) point in the range of f is a two-dimensional surface of genus g and this surface serves as the Heegaard Surface for a Heegaard Splitting.

Moving along the range of f , as we pass through critical points of index 1 or 2, the genus of the inverse image will increase or decrease by 1.

Extension to the Cyclic Case

In this case we map a closed oriented 3-manifold to the Circle S^1 .

Such a mapping still induces a splitting, what will be called a Cyclic Heegaard Splitting, but instead of Handlebodies, we will be dealing with so-called 'Compression Bodies'.

Extension to the Cyclic Case

In this Cyclic case, the issue of uniqueness arises:

- Given two Cyclic Heegaard Splittings, in what way(s) are they related?
- Can we get from one to the other with a sequence of well-defined 'moves'?
- For the non-cyclic case it is known that Heegaard Splittings are unique up to Stabilization, or increasing the genus of the Heegaard Surface. Does there exist an extension of this idea to the Cyclic Case?

References

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- [2] **P. Ozsvath, Z. Szabo**, *An introduction to Heegaard Floer homology*, In “Floer homology, gauge theory, and low-dimensional topology” volume 5 of Clay Math. Proc., pages 3–27. Amer. Math. Soc., Providence, RI, 2006.

- [3] **N. Savaliev**, *Lectures on the topology of 3-manifolds*. de Gruyter Textbook. Walter de Gruyter & Co., Berlin, 1999.